

Ⅱ-201

**Crossed Roller Way** 

Bed

### **Points**

Ball screw

Slide table

Y-table

Ball screw

High precision and compact positioning table

High precision and compact positioning table incorporating Crossed Roller Way into high rigidity and vibration damping performance cast iron slide tables and beds.

#### Safety design with retainer creep proof function

Adoption of Anti-Creep Cage Crossed Roller Way that does not cause retainer creep in the linear motion rolling guide allows you to safely use the table even in vertical axis use and high acceleration / deceleration operation. (TS55/55 and CT55/55 are not included.)

#### Optimal for works directly conducted on the table upper surface

Adoption of large precisely polished table allows you to use the entire table upper surface as work space.



#### 《Durability test》 Test conditions CRWG3 Model number Vibration test machine Test method Posture Maximum speed | 827 mm/s

Operating Acceleration 15 G conditions Cycle 31 Hz 8 mm Stroke Mass of moving table 330 g Number of strokes 100 million strokes

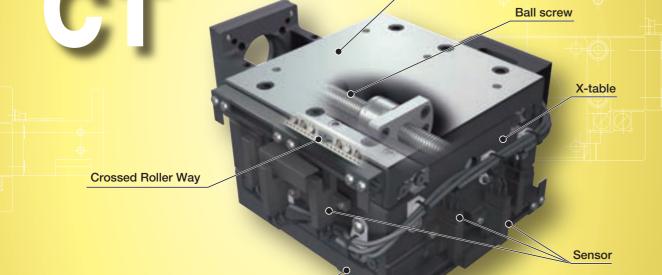


(Result) No retainer creep nor material damage in any component is found

#### Variation

Chana	Model	Table width						
Shape	iviodei	(mm)	55	75	125	220	310	350
Single-axis specification		55	$\stackrel{\wedge}{\sim}$	_	_	_	_	_
0 0 0		75	_	$\Rightarrow$	_	_	_	_
	TS	125	_	_	☆	☆	_	_
		220	_	_	_	$\Rightarrow$	$\Rightarrow$	_
		260	_	_	_	_	_	$\Rightarrow$
Two-axis specification	СТ	55	$\Rightarrow$	_	_	_	_	_
, and		75	_	$\Rightarrow$	_	_	_	_
		125	_	_	$\Rightarrow$	_	_	_
		220	_	_	_	$\Rightarrow$	_	_
• •		260	_	_	_	_	_	$\Rightarrow$
		350	_	_	_	_	_	☆

uses Anti-Creep Cage Crossed Roller Way.



#### Major product specifications

Driving method	Precision ball screw
Linear motion rolling guide	Crossed Roller Way
Built-in lubrication part	No built-in
Material of table and bed	Cast iron
Sensor	Select by identification number

Ⅱ-203

#### Accuracy

	unit: mm
Positioning repeatability	±0.002
Positioning accuracy	0.005~0.015
Lost motion	-
Parallelism in table motion A	0.005~0.008
Parallelism in table motion B	0.015~0.020
Attitude accuracy	-
Straightness	-
Backlash	-

# Example of an Identification Number CT 125 / 125 / AT602 5 SC 1 Model Page II-205 3 Designation of motor attachment Page II-206

#### **Identification Number and Specification.**

Page II-206

Model	TS : Precision Positioning Table TS (single-axis specification) CT : Precision Positioning Table CT (two-axis specification)
2 Dimension of slide table	Select a dimension for slide table from the list of Table 1.
	Width and length of slide table are indicated in mm. For CT (two-axis specification), width and length of Y-table are indicated.

Table 1 Models of linear motion rolling guide/slide table dimension and stroke length

			unit: mm
Model	Linear motion rolling guide	Width/length	Stroke length
	Crossed Roller Way	55/ 55	15
		75/ 75	25
		125/125	50
TS	Anti-Creep Cage	125/220	120
	Crossed Roller Way	220/220	120
		220/310	180
		260/350	250
	Crossed Roller Way	55/ 55	X-axis: 15, Y-axis: 15
		75/ 75	X-axis: 25, Y-axis: 25
СТ	Anti Croon Como	125/125	X-axis: 50, Y-axis: 50
CI	Anti-Creep Cage Crossed Roller Way	220/220	X-axis: 120, Y-axis: 120
	Crossed Holler Way	260/350	X-axis: 150, Y-axis: 250
		350/350	X-axis: 250, Y-axis: 250

3 Designation of motor attachment

Special specification

As for a motor attachment, select it from the list of Table 2.

- · Motor should be prepared by customer.
- · Please specify motor attachment applicable to motor for use.
- · A coupling shown in Table 3 is mounted on the main body before shipment. However, the final position adjustment should be made by customer since it is only temporarily fixed.

Table 2 Application of motor attachment

Motor to be used					Motor attachment				
Туре	Manufacturer	Series	Model	Rated output W		TS55/55 TS75/75 CT55/55 CT75/75	TS125/125 TS125/220 TS220/220 CT125/125 CT220/220	TS220/310	TS260/350 CT260/350 CT350/350
	\/A O1/A\A\A		SGMJV-01A	100	□40	_	AT602	AT604	_
	YASKAWA ELECTRIC	Σ-V	SGMAV-01A	100	⊔40	_	AT602	AT604	_
	CORPORATION	2-V	SGMJV-02A	200	co	_	_	_	AT606
	CONFORMION		SGMAV-02A	200	□60	_	_	_	AT606
	Mitsubishi Electric Corporation	J4	HG-MR13	100		_	AT602	AT604	_
			HG-KR13		□40	_	AT602	AT604	_
AC			HG-MR23	200	□60	_	_	_	AT606
servomotor			HG-KR23 200		_	_	_	AT606	
	Panasonic	MINIAGAS	MSMD01	100	□38	_	AT603	AT605	_
			MSME01			_	AT603	AT605	_
	Corporation	MINAS A5	MSMD02	200		_	_	_	AT607
			MSME02	200	□60	_	_	_	AT607
	Hitachi Industrial Equipment	AD	ADMA-01L	100	□40	_	AT602	AT604	_
	Systems Co., Ltd	AD	ADMA-02L	200	□60	_	_	_	AT606
04	ORIENTAL	PK	PK544-A		□38	AT601	_	_	_
Stepper Motor	MOTOR Co., Ltd.	RKS · CRK	CRK56 (1)		□60	_	AT608	AT609	_
IVIOLOI	WOTON CO., LIG.	nno · unn	RKS59		□85	_	-	-	AT610

Note (1) Applicable to the outer diameter  $\phi 8$  of motor output shaft.

Remark: For detailed motor specifications, please see respective motor manufacturer's catalog.

#### Table 3 Coupling models

Motor attachment	Coupling models	Manufacturer	Coupling inertia $J_{\rm c}$
Wotor attachment	Coupling models	Manuacturer	×10⁻⁵kg · m²
AT601	MWSS-12- 5× 5	Nabeya Bi-tech Kaisha	0.018
AT602	MSTS-25C- 8× 8	Nabeya Bi-tech Kaisha	0.71
AT603	MSTS-25C- 8× 8	Nabeya Bi-tech Kaisha	0.71
AT604	MSTS-25C- 6× 8	Nabeya Bi-tech Kaisha	0.71
AT605	MSTS-25C- 6× 8	Nabeya Bi-tech Kaisha	0.71
AT606	MSTS-32C-12×14	Nabeya Bi-tech Kaisha	2.7
AT607	MSTS-32C-11×12	Nabeya Bi-tech Kaisha	2.7
AT608	MSTS-19C- 6× 8	Nabeya Bi-tech Kaisha	0.277
AT609	MSTS-25C- 6× 8	Nabeya Bi-tech Kaisha	0.71
AT610	MSTS-32C-12×14	Nabeya Bi-tech Kaisha	2.7

Remark: For detailed coupling specifications, please see respective manufacturer's catalogs.

1: Lead 1mm (applicable to 55/55, 75/75, and 125/125)
2: Lead 2mm (not applicable to 55/55 or 75/75)
5: Lead 5mm (not applicable to 55/55 or 75/75)

Special specification

No symbol: Standard specification

Specification

No symbol: Standard specification

BE: Option base (applicable to 55/55)

LR: Black chrome surface treatment

SC : Table with sensor

Option base : Base plate is available for attaching the main body downward.

For detailed information, please see the dimension table.

Black chrome surface treatment: A black permeable film is formed on the surface to improve corrosion resistance.

This treatment is performed on the surfaces of slide table, bed, and motor bracket. For the reference surfaces of respective parts, surface treatment is excluded.

: A set of limit sensor, pre-origin sensor, and origin sensor is attached.

Table with sensors

: A set of limit sensor, pre-origin sensor, and origin sensor is attached.

However, when selecting an AC servomotor attachment, an origin sensor is not provided. Please use the C-phase or Z-phase of the encoder.

Remark: When using multiple special specifications for combination, please indicate by arranging supplemental codes in alphabetical order.

1N=0.102kgf=0.2248lbs. 1mm=0.03937inch

435

#### **Specifications.**

Table 4 Accuracy

Identification number		Positioning	Positioning	Parallelism in	Parallelism in	Squareness of
Single-axis specification	Two-axis specification	repeatability	accuracy	table motion A	table motion B	XY motion(1)
TS 55/ 55	-		0.005			
_	CT 55/ 55		0.010			
TS 75/ 75	CT 75/ 75		0.005	0.005	0.015	0.005
TS125/125	CT125/125		0.005	0.005	0.015	0.005
TS125/220	_	±0.002	0.008			
TS220/220	CT220/220		0.006			
TS220/310	_					
TS260/350	CT260/350		0.015	0.008	0.020	0.008
_	CT350/350					

Note (1) Applied to tables with two-axis specification.

#### Table 5 Maximum speed

Motor type	Maximum speed mm/s				
	Lead 1mm	Lead 2mm	Lead 5mm		
AC servomotor	50	100	250		
Stepper motor	30	60	150		

Remark: To measure the practical maximum speed, it is required to consider operation patterns based on the motor to be used and load conditions.

Table 6.1 Maximum carrying mass of TS

Model and size	Ball screw lead mm	Maximum carrying mass kg		
	111111	Horizontal	Vertical	
TS 55/ 55	1	4.3	2.2	
TS 75/ 75	1	21	1.5	
	1	72	2.3	
TS125/125	2	72	11	
	5	72	29	
TS125/220	2	115	9	
15125/220	5	115	28	
TS220/220	2	169	3.9	
15220/220	5	169	24	
TC000/010	2	256	_	
TS220/310	5	216	19	
T\$260/250	2	310	_	
TS260/350	5	310	18	

Remark: Not operable when the maximum carrying mass is "-".

Table 6.2 Maximum carrying mass of CT

Model and size	Ball screw lead mm	Maximum carrying mass kg		
		Horizontal	Vertical(1)	
CT 55/ 55	1	4.3	2.2	
CT 75/ 75	1	21	1.3	
	1	72	2.3	
CT125/125	2	72	11	
	5	72	29	
CT220/220	2	169	3.9	
G1220/220	5	169	24	
CT060/250	2	225	_	
CT260/350	5	225	18	
CT350/350	2	286	_	
G1330/350	5	310	14	

Note (1) When the Y-axis moves vertically.

Remark: Not operable when the maximum carrying mass is "-".

Table 7 Specifications of ball screw

unit: mm

Table	7 Specifications of ba	all screw			unit: mm
	Model and size	Ball screw lead	Axis name	Shaft dia.	Overall length
	TS 55/ 55	1	-	6	68
	TS 75/ 75	1	-	6	89
_		1	-	12	148
Single-axis specification	TS125/125	2	-	12	148
<u>;</u>		5	-	14	148
eci	TS125/220	2	-	12	269
S S	13123/220	5	-	14	269
<u>:</u>	T0000/000	2	_	14	269
<u>\\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ </u>	TS220/220	5	-	14	269
ing.	TS220/310	2	-	14	389
တ	13220/310	5	-	14	389
	TS260/350	2	_	20	435
	13200/330	5	-	20	435
	CT 55/ 55	1	X-axis, Y-axis	6	68
	CT 75/ 75	1	X-axis, Y-axis	6	89
		1	X-axis, Y-axis	12	148
.ij	CT125/125	2	X-axis, Y-axis	12	148
cat		5	X-axis, Y-axis	14	148
SC.	CT220/220	2	X-axis, Y-axis	14	269
Spe	G1220/220	5	X-axis, Y-axis	14	269
· <u>×</u>		2	X-axis	20	330
G	CT260/350	2	Y-axis	20	435
Two-axis specification	01200/330	5	X-axis	20	330
		5	Y-axis	20	435
	CT350/350	2	X-axis, Y-axis	20	435

X-axis, Y-axis

20

#### Table 8 Table inertia and starting torque

CT350/350

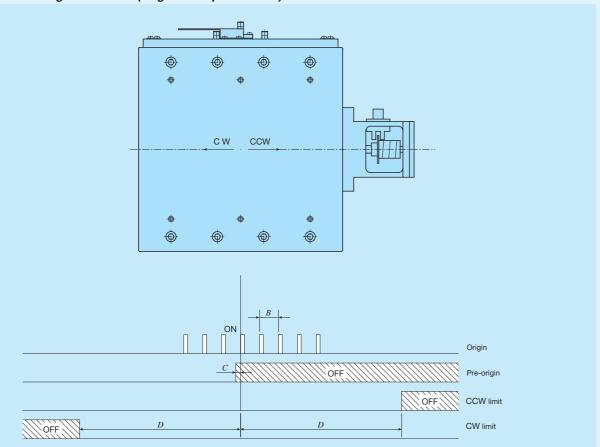
	Identification number			Table inertia $J_{\scriptscriptstyle  extsf{T}}$ $ imes$ 10 $^{ extsf{-5}}$ kg $\cdot$ m $^2$						
			Lead 1mm	N∙m						
	TS 55/ 55		0.01	-	_	0.03				
" <u>⊏</u>	TS 75/ 75		0.01	_	_	0.03				
Single-axis specification	TS125/125		0.20	0.23	0.55	0.07				
ific.	TS125/220		-	0.40	0.95	0.07				
Sing	TS220/220		-	0.73	1.1	0.09				
S S	TS220/310		-	1.3	2.1	0.09				
	TS260/350		_	3.8	5.6	0.12				
	CT 55/ 55	X-axis	0.01	-	_	0.03				
	C1 55/ 55	Y-axis	0.01	_	_	0.03				
_	CT 75/ 75	X-axis	0.01	_	_	0.07				
atic	G1 75/ 75	Y-axis	0.01	_	_	0.07				
specification	CT125/125	X-axis	0.20	0.28	0.85	0.07				
Sec	G1125/125	Y-axis	0.20	0.23	0.55	0.07				
S	CT000/000	X-axis	_	0.85	1.9	0.09				
Two-axis	CT220/220	Y-axis	_	0.73	1.1	0.09				
o V	OT000/050	X-axis	-	4.6	6.8	0.12				
≥	CT260/350	Y-axis	-	3.8	5.6	0.12				
	X-axis		-	4.9	8.0	0.12				
	CT350/350	Y-axis	-	4.6	5.9	0.12				

#### **Mounting**

For the processing accuracy of the Precision Positioning Table mounting surface and the tightening torque of the fixing screws, see page II-29.

#### **Sensor Specification**

Table 9.1 Sensor timing chart for TS (single-axis specification)



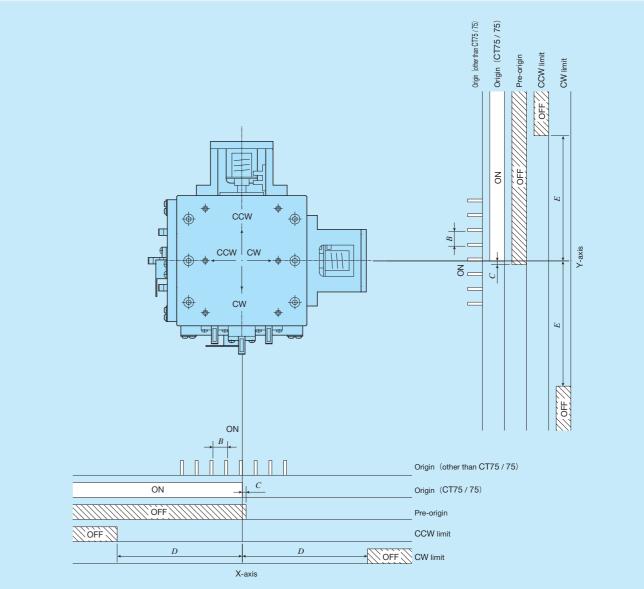
unit: mm

Identification number	Ball screw lead	В	С	D		
TS 55/ 55	1	1	0.7	7.5		
TS 75/ 75	1	1	0.7	12.5		
	1	1	0.7			
TS125/125	2	2	1.5	25		
	5	5	3			
TS125/220	2	2	1.5	60		
19125/220	5	5	3	00		
TS220/220	2	2	1.5	60		
18220/220	5	5	3	00		
TS220/310	2	2	1.5	00		
13220/310	5	5	3	90		
TS260/350	2	2	1.5	105		
13200/330	5	5	3	125		

Remarks 1. Mounting a sensor is specified using the corresponding identification number.

- 2. For the specifications of respective sensors, please see the section of sensor specification in General Explanation.
- 3. When selecting an AC servomotor attachment, an origin sensor is not provided. Please use the C-phase or Z-phase of the encoder.
- 4. Positions for mounting sensors vary depending on the identification numbers. For detailed information, please see the dimension tables of respective identification numbers.

#### Table 9.2 Sensor timing chart for CT (two-axis specification)



Identification number	Ball screw lead	В	С	D	E	
CT 55/ 55	1	1	0.7	7.5	7.5	
CT 75/ 75	1	_	0.7	12.5	12.5	
	1	1	0.7			
CT125/125	2	2	1.5	25	25	
	5	5	3			
CT220/220	2	2	1.5	60	60	
C1220/220	5	5	3	00	00	
CT260/350	2	2	1.5	75	125	
C1200/350	5	5	3	75	125	
CT350/350	2	2	1.5	125	125	
G1350/350	5	5	3	123	125	

Remarks 1. Mounting a sensor is specified using the corresponding identification number.

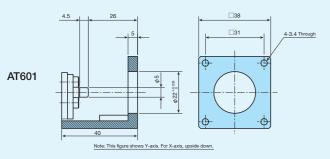
- 2. For the specifications of respective sensors, please see the section of sensor specification in General Explanation.
- 3. When selecting an AC servomotor attachment, an origin sensor is not provided. Please use the C-phase or Z-phase of the encoder.
- 4. Positions for mounting sensors vary depending on the identification numbers. For detailed information, please see the dimension tables of respective identification numbers.

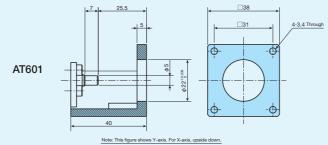
unit: mm

#### **Dimensions of Motor Attachment**

#### TS55/55, CT55/55

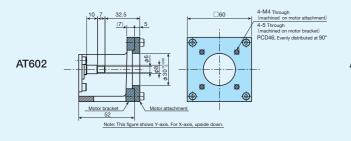
#### TS75/75, CT75/75

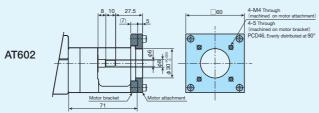


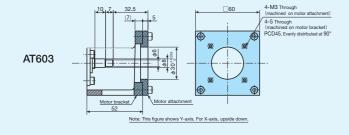


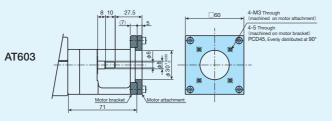
#### TS125/125, CT125/125

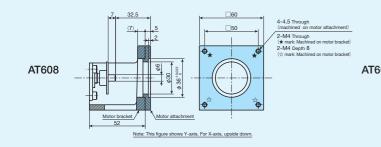
TS125/220

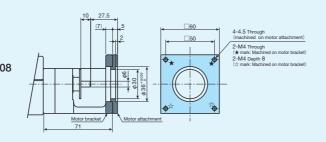






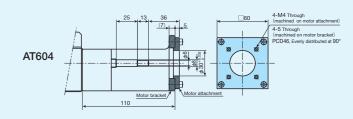


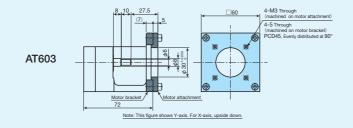


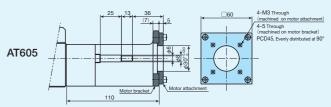


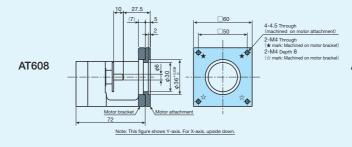
#### TS220/220, CT220/220

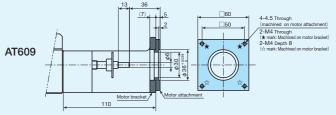
## AT602 AT602 AT602 AT602 A-M4 Through functioned no motor statchment) CD46, Everly distributed at 90° Motor bracket Motor bracket Note: This figure shows Y-axis, For X-axis, upside down.







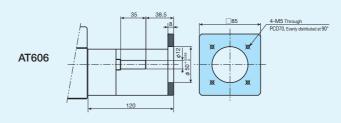


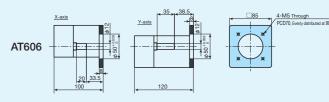


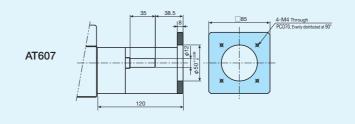
#### TS260/350

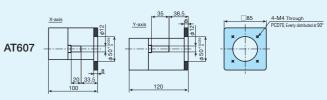
#### CT260/350

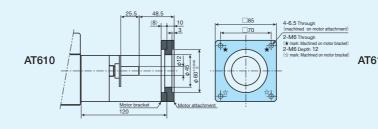
TS220/310

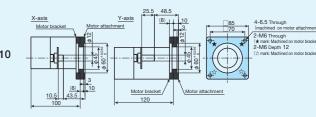






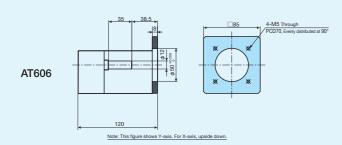


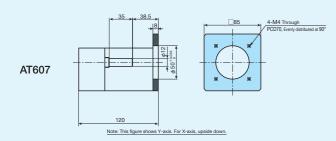


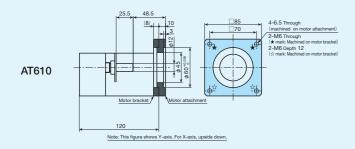


#### 0/0

#### CT350/350



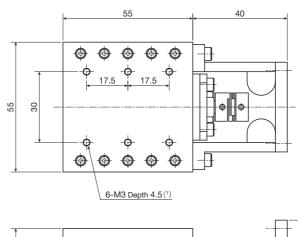


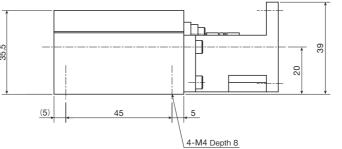


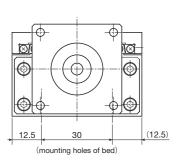
#### **IKU** Precision Positioning Tables TS / CT

#### TS55/55

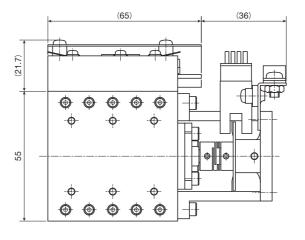
#### Specification without sensor

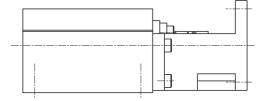


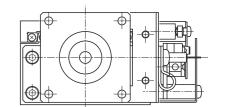




#### Specification with sensor







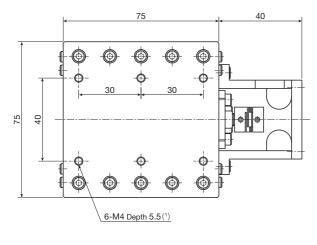
Stroke length: 15mm Reference mass(2): 0.8kg

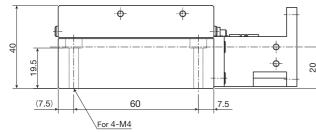
Notes (1) Too deep insertion depth of the mounting bolt may affect the running performance of the slide table, so never insert a bolt longer than the depth of the through hole.

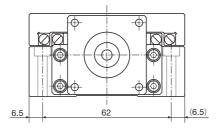
(2) Mass of the sensor is not included.

#### TS75/75

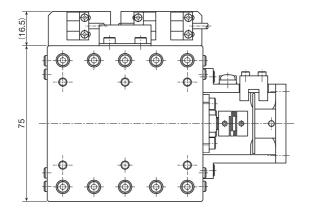
#### Specification without sensor

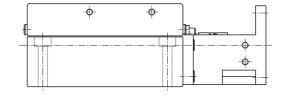


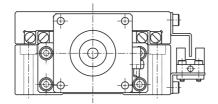




#### Specification with sensor







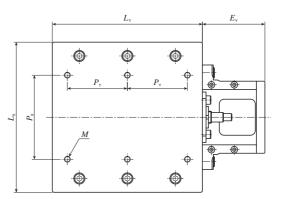
Stroke length: 25mm Reference mass(2): 1.6kg

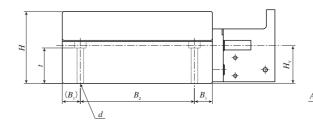
Notes (1) Too deep insertion depth of the mounting bolt may affect the running performance of the slide table, so never insert a bolt longer than the depth of the through hole.

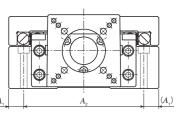
(2) Mass of the sensor is not included.

#### TS125/125, TS220/220

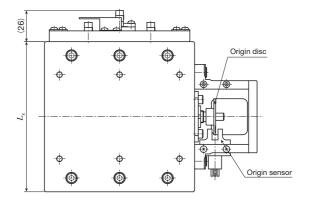
#### Specification without sensor





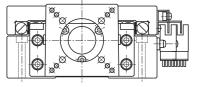


#### Specification with sensor



Note) When selecting an AC servomotor attachment, an origin sensor and origin disc are not provided.





unit: mm

		nensions of ta	ble	0	_	Height of shaft center
Identification number	$L_{x}$	$L_{\scriptscriptstyleY}$	Н	Stroke length	$E_{\scriptscriptstyleY}$	$H_{\scriptscriptstyle  m Y}$
TS125/125(1)	125	125	60	50	52	31.5
TS220/220	220	220	65	120	72	33.5

	Libertie - Parameter		ting bolt			Bed mou	ınting-rela	ted dime	nsions		Reference mass <sup>(2)</sup>		
	Identification number	$M(^{3})$	$P_{X}$	$P_{\scriptscriptstyle  m Y}$	d	t	$A_{1}$	$A_2$	$B_{1}$	$B_2$	kg		
	TS125/125(1)	6-M5 depth 10	70	50	For 4-M5	29.6	12.5	100	15	95	7.5		
	TS220/220	6-M6 depth 12	150	75	For 4-M6	27.5	20	180	20	180	16.0		

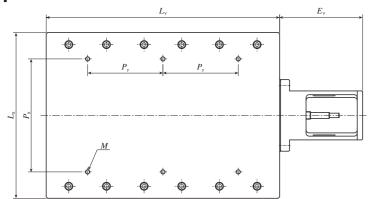
Notes (1) The motor bracket is positioned 1.5mm higher than the upper surface of the table.

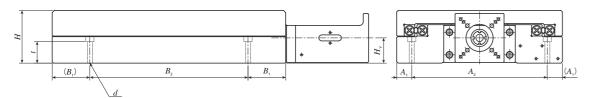
(2) Mass of the sensor is not included.

(3) Too deep insertion depth of the mounting bolt may affect the running performance of the slide table, so never insert a bolt longer than the depth of the through hole. 1N=0.102kgf=0.2248lbs.

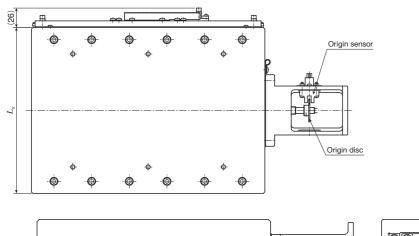
#### TS125/220, TS220/310, TS260/350

#### Specification without sensor





#### Specification with sensor



Note) When selecting an AC servomotor attachment, an origin sensor and origin disc are not provided.





unit: mm

unit. II												
Identification number		nensions of ta	ble	Churches Ionsorth	E <sub>v</sub>	Height of shaft center						
	$L_{\chi}$	$L_{Y}$	Н	Stroke length	$H_{Y}$							
TS125/220(1)	125	220	60	120	71	31.5						
TS220/310	220	310	70	180	110	33.5						
TS260/350	260	350	100	250	120	47.5						

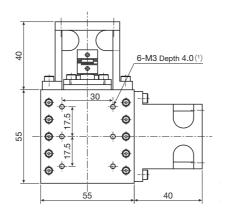
		nting bolt			Bed mou	nting-rela	ted dime	nsions		Reference mass(2)			
Identification number	M(3)	$P_{X}$	$P_{\scriptscriptstyle Y}$	d	t	$A_{\scriptscriptstyle 1}$	$A_2$	$B_{\scriptscriptstyle 1}$	$B_2$	kg			
TS125/220(1)	6-M5 depth 10	70	75	For 4-M5	29.6	12.5	100	20	180	11			
TS220/310	6-M6 depth 12	150	100	For 4-M6	28.5	20	180	50	210	27			
TS260/350	6-M6 depth 12	150	125	For 4-M8	45.4	22.5	215	50	250	48			

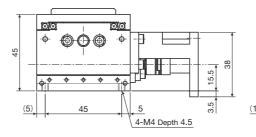
Notes (1) The motor bracket is positioned 1.5mm higher than the upper surface of the table.

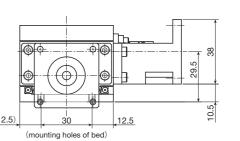
- (2) Mass of the sensor is not included.
- (3) Too deep insertion depth of the mounting bolt may affect the running performance of the slide table, so never insert a bolt longer than the depth of the through hole.

#### CT55/55

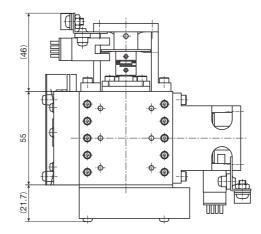
#### Specification without sensor

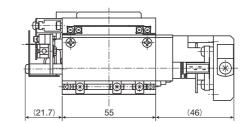


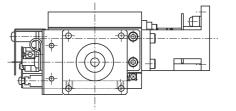




#### Specification with sensor





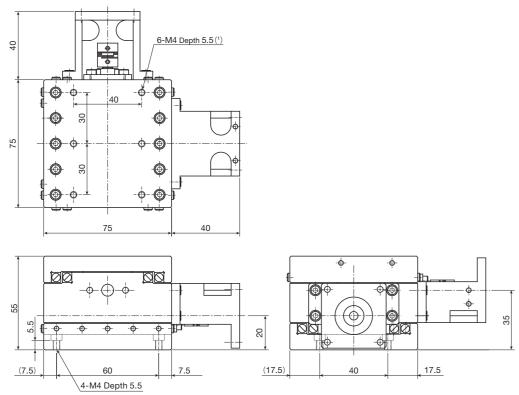


X- and Y-axis stroke length: 15mm Reference mass(2): 1.7kg

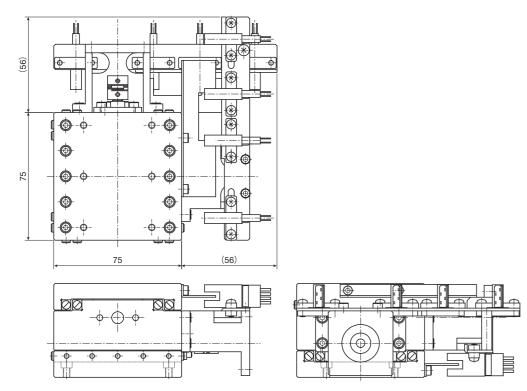
- Notes (1) Too deep insertion depth of the mounting bolt may affect the running performance of the slide table, so never insert a bolt longer than the depth of the through hole.
  - (2) Mass of the sensor is not included.

#### CT75/75

#### Specification without sensor



#### Specification with sensor



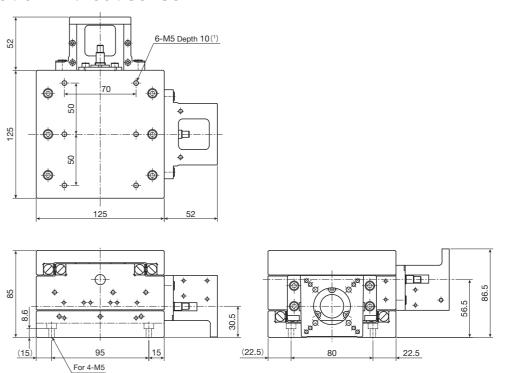
X- and Y-axis stroke length: 25mm Reference mass(2): 2.0kg

Notes (1) Too deep insertion depth of the mounting bolt may affect the running performance of the slide table, so never insert a bolt longer than the depth of the through hole.

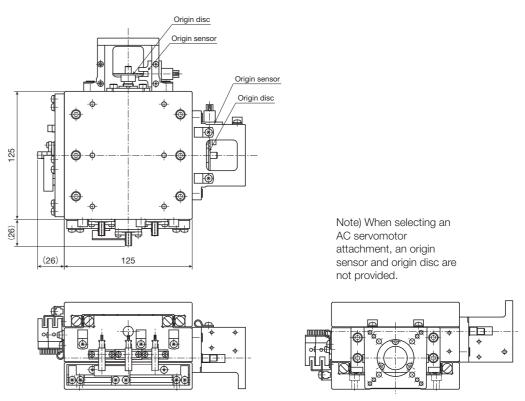
(2) Mass of the sensor is not included.

#### CT125/125

#### Specification without sensor



#### Specification with sensor



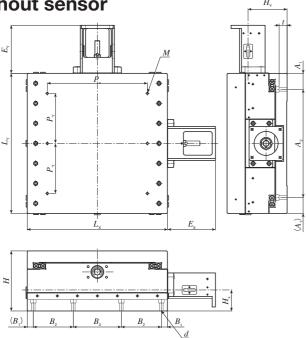
X- and Y-axis stroke length: 50mm Reference mass(2): 1.7kg

Notes (1) Too deep insertion depth of the mounting bolt may affect the running performance of the slide table, so never insert a bolt longer than the depth of the through hole.

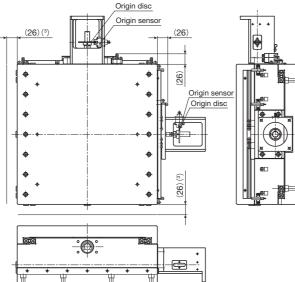
(2) Mass of the sensor is not included.

#### CT220/220, CT260/350, CT350/350

Specification without sensor



Specification with sensor



Note) When selecting an AC servomotor attachment, an origin sensor and origin disc are not provided.

unit: mn

	Dim	ensions of t	able	Stroke	length			Height of shaft center		
Identification number	$L_{x}$	$L_{\scriptscriptstyle Y}$	Н	X-axis	Y-axis	$E_{x}$	$E_{\scriptscriptstyle  m Y}$	$H_{x}$	$H_{\scriptscriptstyle  m Y}$	
CT220/220	220	220	100	120	120	72	72	31.5	68.5	
CT260/350	260	350	150	150	250	100	120	52.5	97.5	
CT350/350	350	350	150	250	250	120	120	52.5	97.5	

Identification number		ting bolt			Bed m	ounting-	related o	Reference			
	<i>M</i> (1)	$P_{X}$	$P_{\scriptscriptstyle Y}$	d	t	$A_{\scriptscriptstyle 1}$	$A_2$	$B_1$	$B_2$	$B_3$	mass <sup>(2)</sup> kg
CT220/220	6-M6 depth 12	150	75	For 8-M6	7.5	30	160	15	40	110	20
CT260/350	6-M6 depth 12	150	125	For 8-M8	20	40	270	15	55	120	66
CT350/350	6-M6 depth 12	250	125	For 8-M8	20	40	270	15	100	120	77

Notes (1) Too deep insertion depth of the mounting bolt may affect the running performance of the slide table, so never insert a bolt longer than the depth of the through hole.

- (2) Mass of the sensor is not included.
- (3) Applicable to CT220/220. This shows the dimension when the sensor is attached.

#### ●Option base dimensions for TS55/55 and CT55/55

