

Ⅱ-265

Crossed roller bearing

Moving magnet

Mechanical stopper

Stator coil

Stator coil

Moving magnet

Compact XYθ-table

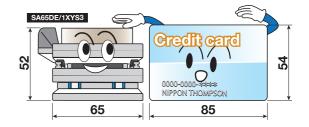
Using a Linear Way L miniature linear motion rolling guide in the linear motion guiding parts and Crossed Roller Bearing in the rotation guiding parts respectively and adopting direct drive method in the drive section, this is an alignment stage for achieving low profile and compact XY θ motion.

Flexible combination of XY θ

X-table for linear movement and θ -table serving as rotary positioning section are listed on lineup as basic configuration. Combination of X-axis and θ -axis and alignment table for XY-axis can be easily configured.

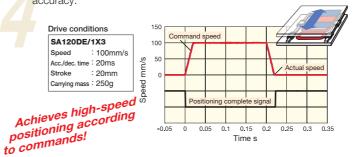
Thin and compact

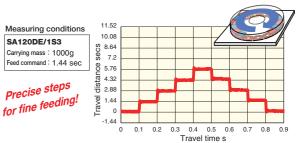
Coreless linear motor, Linear Way L and Crossed Roller Bearing are adopted. As compared with ball screw-driven stage, extremely low profile is achieved.



High resolution and high responsiveness

Performing full-closed loop control of direct drive-type stage with high resolution linear encoder built-in has achieved high resolution and high accuracy.





Alignment Stage SA specification list

	SA65I	DE/X	SA1	20DE/X	SA200E	DE/X (1)	SA65DE/S	SA120DE/S	SA200DE/S
Model and size			W		1				•
Sectional shape		65 £	\$2 F	120	8 F	200	65	120	200
Maximum thrust N	25	5	70)	40	0	Max. torque 0.5N·m	Max. torque 2.0N·m	Max. torque 4.0N⋅m
Rated thrust N	3	3.5	15	5	7	0	Rated torque 0.06N·m	Rated torque 0.4N·m	Rated torque 1.2N·m
Maximum load mass kg	2	2.4	5	5.9	3	0.0	2.2	6.8	12.3
Effective stroke length mm	10)	20)	2	0	Effective operating angle 50degree	Effective operating angle 60degree	Effective operating angle 280degree
Resolution	0.1	0.5	0.1	0.5	0.1	0.5	0.64sec 5625pulse/deg	0.36sec 10000pulse/deg	0.25sec 14400pulse/deg
Maximum speed mm/s	270	500	400	800	400	800	720deg/sec	400deg/sec	270deg/sec
Positioning repeatability μ m	±().5	±C).5	±	0.5	±1.3sec	±0.8sec	±0.5sec

Note (1) SA200DE/X can be manufactured as a custom product upon request. If needed, please contact IKO.

Major product specifications

Driving method	Linear motor
Linear motion rolling guide and bearing	XY-axis: Linear Way (ball type) θ -axis: Crossed Roller Bearing
Lubrication	Lubrication part "C-Lube" is built-in (except for θ -axis and SA65DE/X)
Material of table and bed	High carbon steel
Sensor	Provided as standard

Accuracy

Mechanical stopper

	unit: m	m
Positioning repeatability	XY-axis: ± 0.0005 θ -axis: $\pm 0.5 \sim 1.3$ sec	
Positioning accuracy	-	
Lost motion	-	
Parallelism in table motion A	-	
Parallelism in table motion B	-	
Attitude accuracy	-	
Straightness	-	
Backlash	-	

Linear motor drive

X-table

Linear Way

Optical linear encoder

scale head

θ-table

Identification Number Example of an Identification Number XYS R 120 DE / 5 Model Page II -269 Page II -269 **Resolution** Page II-269 4 Axial configuration Page II-269 Surface treatment Page II-269 6 Specification number Page II -269

Identification Number and Specification.

Model	SA···DE: Alignment Stage SA
2 Size	65: □ 65, φ 65 120: □120, φ120 200: φ200
3 Resolution	 1: 0.1 μm 5: 0.5 μm Specify the resolution of the encoder for X-axis or XY-axis. When selecting only S: θ-axis in the entry of section Φ, set "No symbol" for the resolution.
4 Axial configuration	Select an axial configuration from the list of Table 1.

Table 1 Axial configuration and application

· · · · · · · · · · · · · · · · · · ·						
Axial configuration	SA65DE	SA120DE	SA200DE			
X : Only X-axis	0	0	- (¹)			
S : Only <i>θ</i> -axis	0	0	0			
XY : XY -based two-axis configuration	0	0				
XS : X θ -based two-axis configuration	0	0	– (1)			
XYS: X. Y. and θ -based three-axis configuration	0	0				

Note (1) Can be manufactured as a custom product upon request. If needed, please contact IKO.

5 Surface treatment	No symbol: Electroless nickel plating R : Black chrome surface treatment Surface treatment is performed on the surfaces of table and bed.
6 Specification number	3: Specification number 3 The specification number is limited to 3.

Specifications

Table 2.1 Specification / Performance

Identifica Item	ation number	SA65DE/1X	SA65DE/5X	SA120DE/1X	SA120DE/5X	
Maximum thrust (1)	Maximum thrust (1) N		25 70)	
Rated thrust (2)	N	3.5		15	15	
Effective stroke length	Effective stroke length mm)	20)	
Maximum load mass	kg	2.4		5.9		
Resolution	μm	0.1	0.5	0.1	0.5	
Maximum speed (3)	mm/s	270	500	400	800	
Positioning repeatability	(4) μm	±0.5				
Mass of moving table	Mass of moving table kg		0.17		1.2	
Total mass (5) kg		0.35 2.5			.5	
Ambient temperature an humidity in operation	d		0~40℃ · 20~80%RF	(keep dewdrop free)		

Notes (1) The duration of maximum thrust is up to 1 second.

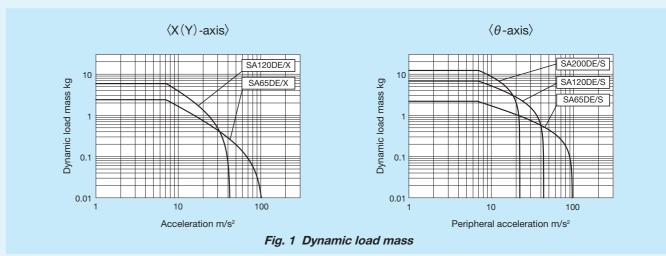
- (2) This is based on the case of mounting on a metal mating member material at an ambient temperature of 20°C.
- (3) For the case of exceeding the displayed speed, please contact IKO.
- (4) When the temperature of the product is constant.
- (5) Mass of the cord is not included.

Table 2.2 Specification / Performance

Identificat	tion number	SA65DE/S	SA120DE/S	SA200DE/S
Maximum torque (1)	N∙m	0.5	2.0	4.0
Rated torque (2)	N∙m	0.06	0.4	1.2
Maximum load mass	kg	2.2	6.8	12.3
Effective operating angle	degree	50	60	280
Resolution	sec	0.64	0.36	0.25
nesolution	pulse/degree	5 625	10 000	14 400
Maximum speed (3)	degree/sec	720	400	270
Positioning repeatability (4)sec	±1.3	±0.8	±0.5
Inertia moment of moving table	kg·m²	0.00012	0.002	0.013
Total mass (5)	kg	0.5	2	6
Ambient temperature and humidity in operation		0~40°C ⋅ 20~80%RH (keep dewdrop free)		

Notes (1) The duration of maximum torque is up to 1 second.

- (2) This is based on the case of mounting on a metal mating member material at an ambient temperature of 20°C.
- (3) For the case of exceeding the displayed speed, please contact IKO.
- (4) When the temperature of the product is constant.
- (5) Mass of the cord is not included.



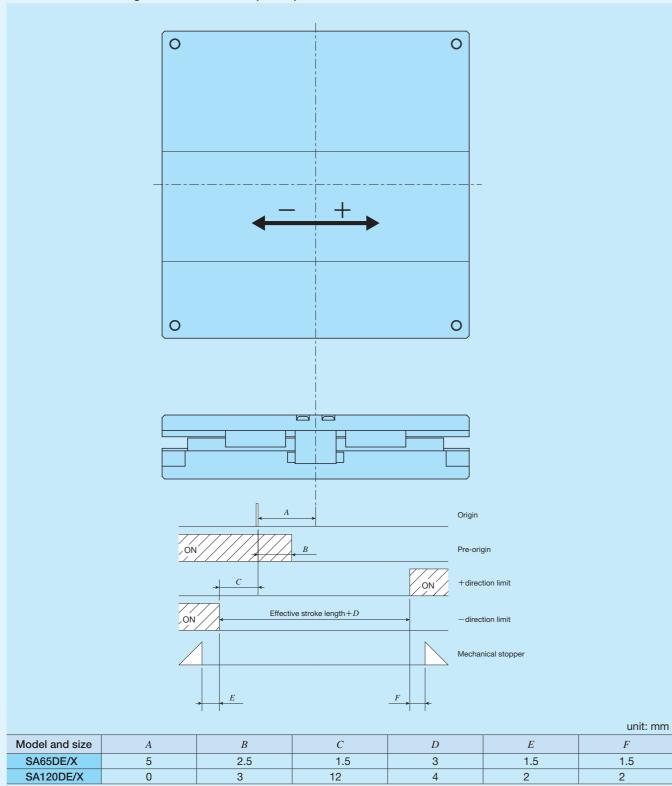
Remark: Dynamic load mass of θ -axis is a value calculated as cube of steel. And, the acceleration is converted as value of stage periphery.

Mounting

For the processing accuracy of the Precision Positioning Table mounting surface and the tightening torque of the fixing screws, see page II-29.

Sensor Specification

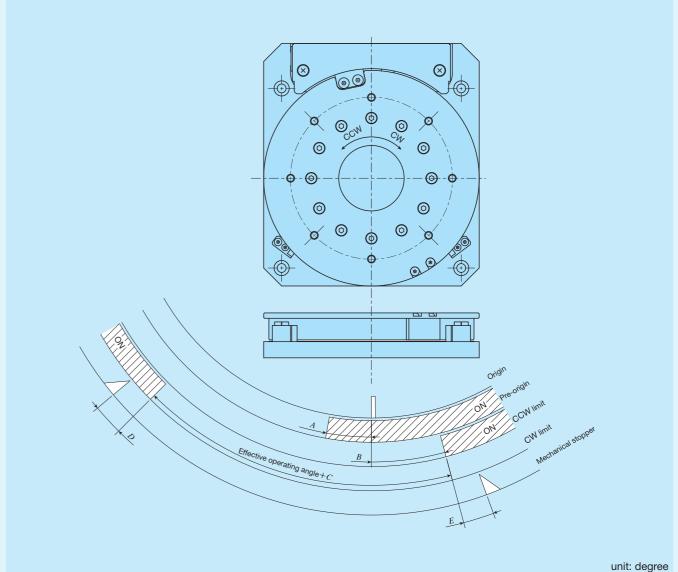
Table 3.1 Sensor timing chart for SA···DE/X (X-axis)



Remarks 1. Respective values are for reference and are not guaranteed values. For detailed dimensions, please contact IKO.

Sensor Specification

Table 3.2 Sensor timing chart for SA···DE/S (θ-axis)



Model and size	A	В	С	D	E
SA65DE/S	4	11	10	5	5
SA120DE/S	3	3	6	3	3
SA200DE/S	2	4	0	4	4

Remarks 1. Respective values are for reference and are not guaranteed values. For detailed dimensions, please contact IKO.

^{2.} For detailed specifications of respective sensors, please see the section of sensor specification in General Explanation.

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System Configuration

Two series of dedicated drivers, ADVA and MR-J4, are available for the Alignment Stage SA, and the system configuration varies depending on the driver used. For ADVA, two types of specification, pulse train specification and high speed network EtherCAT specification, are available. For MR-J4, only high speed network SSCNET III/H specification is available. Table 4 shows the example of identification number for ADVA, and Table 5 shows the tables and model number of applicable MR-J4. For detailed driver specification, please see the driver specification on page II -360 to II -363.

Table 4 Identification number for ADVA

ADVA	_	01NL	EC	/	SA65DE-S
(1) Model		(2)	(3)		(4)

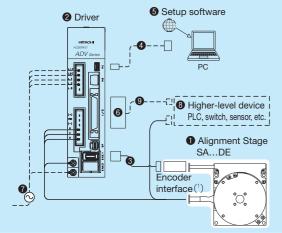
(2) Power supply voltage					
01NL Single-phase / Three-phase 200					
R5ML	Single-phase 100 V				
(3) Command type					
No symbol Pulse train command					
EU CAT					

(4) Applicable alignment stage model					
SA65DE -S	SA65DE /S				
SA65DE -X	SA65DE /X				
SA120DE -S	SA120DE /S				
SA120DE -X	SA120DE /X				
SA200DE -S	SA200DE /S				

Table 5 Identification numbers of SA...DE and applicable MR-J4

Identification number of table	Identification number of driver
SA65DE /S	MR-J4-10B-RJ /SA65DE -S
SA65DE /X	MR-J4-10B-RJ /SA65DE -X
SA120DE /S	MR-J4-10B-RJ /SA120DE -S
SA120DE /X	MR-J4-10B-RJ /SA120DE -X
SA200DE /S	MR-J4-10B-RJ /SA200DE -S

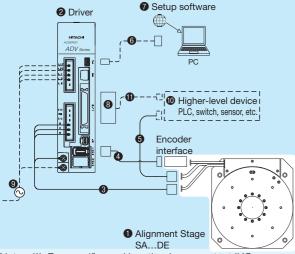
Table 6 System configuration for SA65DE, SA120DE with driver ADVA



No.	Name	Identification Number
8	Encoder extension cord (2m) (2)	TAE20V4-EC02
4	PC connection cable	USB mini B cable This must be prepared by customer.
6	Setup software	ProDriveNext Please download from the official website of Hitachi Industrial Equipment Systems Co., Ltd.
6	I/O connector	TAE20R5-CN(3)
0	Power cord	This must be prepared by customer.
8	Higher-level device	
9	I/O connector connection cable	

- Notes (1) XY-axis of SA65DE is not provided with an encoder interface.
 - (2) For specific cord length, please contact IKO.
 - (3) I/O connector TAE20R5-CN is a combined product of 10150-3000PE (connector) and 10350-52F0-008 (cover) from 3M Japan Limited.

Table 7 System configuration for SA200DE/S with driver ADVA



No.	Name	Identification Number
8	Motor extension cord (3m) (1)	TAE20V3-AM03
4	Encoder extension cord (2m) (1)	TAE20V4-EC02
6	Sensor extension cord (2)	TAE10V8-LC□□
6	PC connection cable	USB mini B cable This must be prepared by customer.
0	Setup software	ProDriveNext Please download from the official website of Hitachi Industrial Equipment Systems Co., Ltd.
8	I/O connector	TAE20R5-CN(3)
9	Power cord	This must be prepared by customer.
0	Higher-level device	
0	I/O connector connection cable	

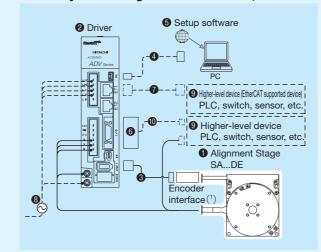
- Notes (1) For specific cord length, please contact IKO.
 - (2) The lengths of the sensor extension cord is specified in the fields of $\Box\Box$ located at the end of the identification number with a length from 3 to 10m in units of 1m
 - (3) I/O connector TAE20R5-CN is a combined product of 10150-3000PE (connector) and 10350-52F0-008 (cover) from 3M Japan Limited.

Setup software

To operate Alignment Stage SA, initial setting of driver parameters is required. Parameter setting for driver is performed using the setup software. It can also be used for gain adjustment and operational status check.

In the driver, the setup software and PC connection cable are not provided. These can be shared in plural drivers but at least 1 set is required. Please prepare these on your own or place an order separately according to your requirement.

Table 8 System configuration for SA65DE, SA120DE with driver ADVA...EC

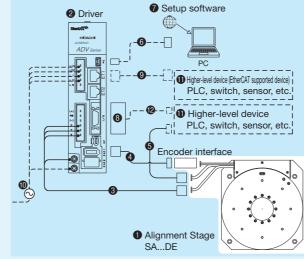


No.	Name	Identification Number
3	Encoder extension cord (2m) (2)	TAE20V4-EC02
4	PC connection cable	USB mini B cable This must be prepared by customer.
6	Setup software	ProDriveNext Please download from the official website of Hitachi Industrial Equipment Systems Co., Ltd.
6	I/O connector	TAE20V5-CN(3)
0	Ethernet cable	
8	Power cord	This must be prepared by
9	Higher-level device	customer.
0	I/O connector connection cable	

Notes (1) XY-axis of SA65DE is not provided with an encoder interface.

- (2) For specific cord length, please contact IKO.
- (3) I/O connector TAE20V5-CN is a combined product of 10120-3000PE (connector) and 10320-52F0-008 (cover) from 3M Japan Limited.

Table 9 System configuration for SA200DE/S with driver ADVA...EC

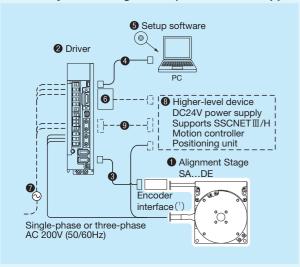


No.	Name	Identification Number
8	Motor extension cord (3m) (1)	TAE20V3-AM03
4	Encoder extension cord (2m) (1)	TAE20V4-EC02
6	Sensor extension cord (2)	TAE10V8-LC□□
6	PC connection cable	USB mini B cable This must be prepared by customer.
0	Setup software	ProDriveNext Please download from the official website of Hitachi Industrial Equipment Systems Co., Ltd.
8	I/O connector	TAE20V5-CN(3)
9	Ethernet cable	
0	Power cord	This must be prepared by
0	Higher-level device	customer.
12	I/O connector connection cable	

Notes (1) For specific cord length, please contact IKO.

- (2) The lengths of the sensor extension cord is specified in the fields of $\Box\Box$ located at the end of the identification number with a length from 3 to 10m in units of 1m.
- (3) I/O connector TAE20V5-CN is a combined product of 10120-3000PE (connector) and 10320-52F0-008 (cover) from 3M Japan Limited.

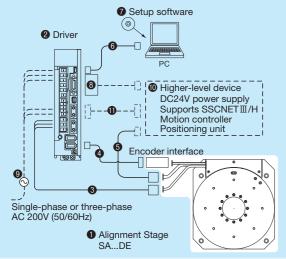
Table 10 System configuration (SSCNET II/H supported) for SA...DE with driver MR-J4-10B



No.	Name	Identification Number
3	Encoder extension cord (2m) (2)	TAE20V6-EC02
4	PC connection cable (3m)	MR-J3USBCBL3M
6	Setup software	SW1DNC-MRC2-J
6	Connectors for input/output connection	MR-CCN1(3)
7	Power cord	This was at his was a seed by
8	Higher-level device (4)	This must be prepared by customer.
9	Connection cable for SSCNET Ⅲ/H	Gustomer.

- Notes (1) XY-axis of SA65DE is not provided with an encoder interface.
 - (2) For specific cord length, please contact IKO.
 - (3) Connector for input/output connection MR-CCN1 is a combined product of 10120-3000PE (connector) and 10320-52F0-008 (cover) from 3M Japan Limited.
 - (4) The higher-level devices are a motion controller, positioning unit and DC24V power supply ready for SSCNET Ⅲ/H from Mitsubishi Electric Corporation.

Table 11 System configuration (SSCNET II/H supported) for SA200DE/S with driver MR-J4-10B

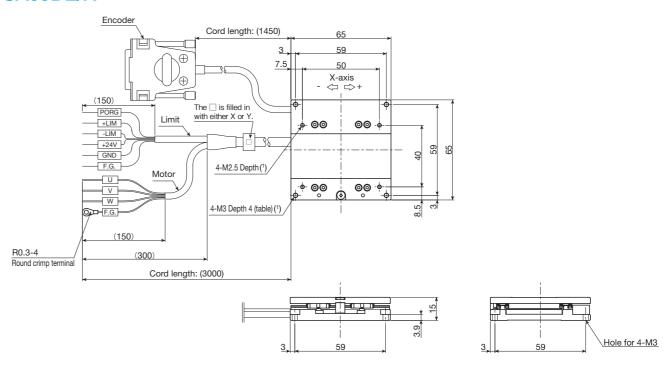


No.	Name	Identification Number
8	Motor extension cord (3m) (1)	TAE20V3-AM03
4	Encoder extension cord (2m) (1)	TAE20V6-EC02
6	Sensor extension cord (2)	TAE10V8-LC□□
6	PC connection cable (3m)	MR-J3USBCBL3M
7	Setup software	SW1DNC-MRC2-J
8	Connectors for input/output connection	MR-CCN1(3)
9	Power cord	This was at his ways are all has
0	Higher-level device (4)	This must be prepared by customer.
•	Connection cable for SSCNET II/H	

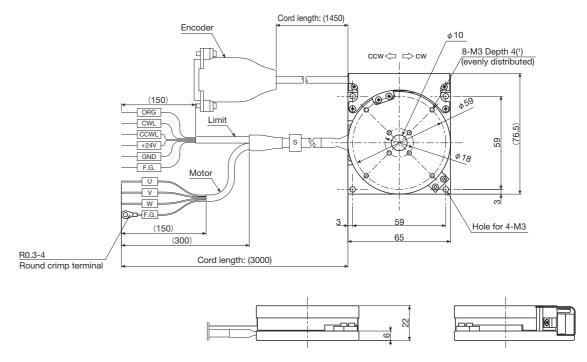
- Notes (1) For specific cord length, please contact IKO.
 - (2) The lengths of the sensor extension cord is specified in the fields of □□ located at the end of the identification number with a length from 3 to 10m in units of 1m.
 - (3) Connector for input/output connection MR-CCN1 is a combined product of 10120-3000PE (connector) and 10320-52F0-008 (cover) from 3M Japan Limited.
 - (4) The higher-level devices are a motion controller, positioning unit and DC24V power supply ready for SSCNET Ⅲ/H from Mitsubishi Electric Corporation.

IK Alignment Stage SA

SA65DE/X



SA65DE/S

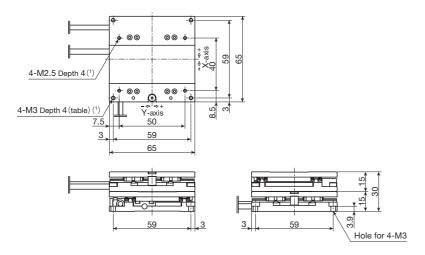


Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

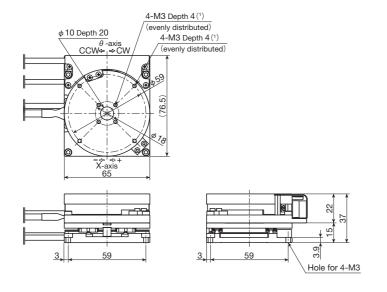
Remark: The text direction on the mark tube of the motor / limit cord may vary by product.

IKO Alignment Stage SA

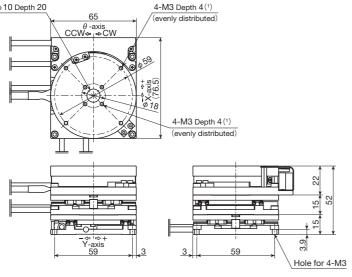
SA65DE/XY



SA65DE/XS



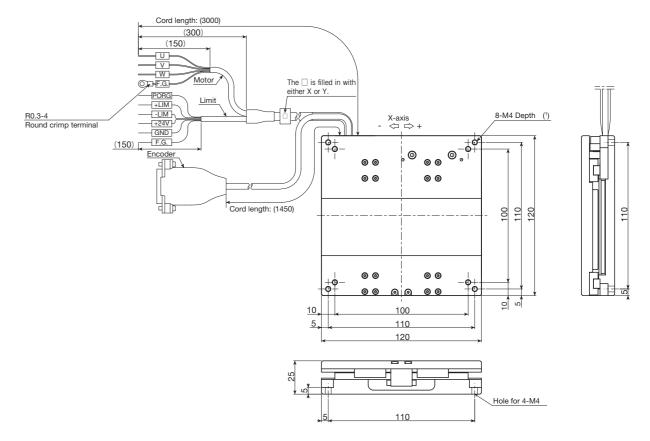
SA65DE/XYS



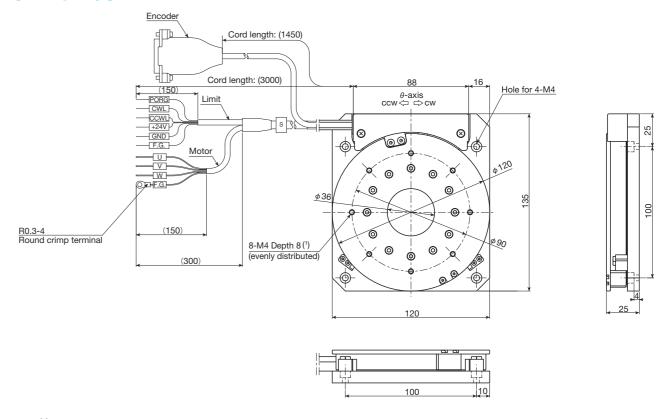
Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

Remark: For the cable length, please see the dimension tables for SA65DE/X and SA65DE/S.

SA120DE/X



SA120DE/S

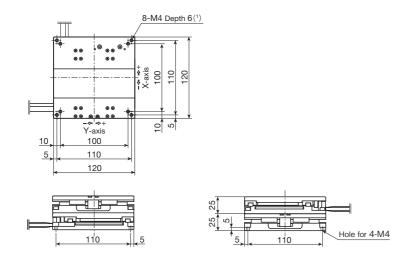


Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

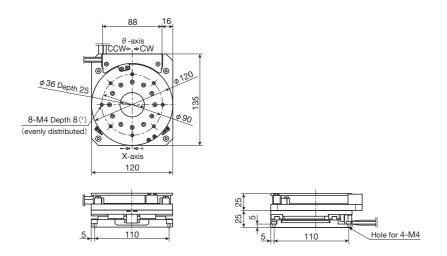
Remark: The text direction on the mark tube of the motor / limit cord may vary by product.

IX Alignment Stage SA

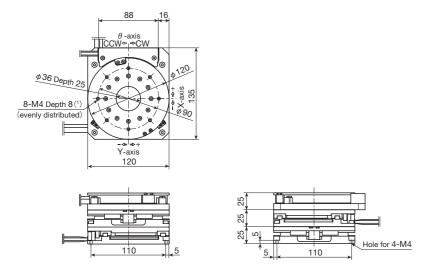
SA120DE/XY



SA120DE/XS



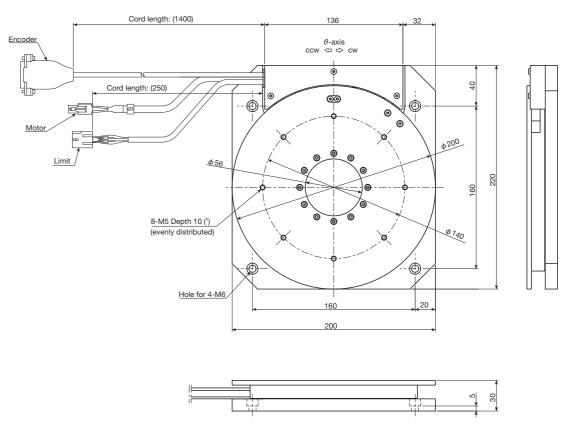
SA120DE/XYS



Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

Remark: For the cable length, please see the dimension tables for SA120DE/X and SA120DE/S.

SA200DE/S



Note (1) Too deep insertion depth of the mounting bolt may affect the running performance of the moving table, so never insert a bolt longer than the depth of the through hole.

Encoder interface

